

# Nonlocal fractional semilinear integrodifferential equations in separable Banach spaces

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**Abstract:** The existence of mild solutions for fractional semilinear integrodifferential equations with nonlocal conditions in separable Banach spaces is studied in this article. The result is established by Hausdorff measure of noncompactness and Schauder fixed point theorem.

**Keywords:** Fractional Differential Equation, Nonlocal Conditions, Hausdorff Measure of Noncompactness, Mild Solution

## 1. Introduction

The aim of this article is mainly concerned with the existence of mild solutions of the nonlocal fractional Cauchy problem of the form

$${}^C D_t^\alpha u(t) = Au(t) + \int_0^t f(t, s, u(s)) ds, t \in [0, b], \quad (1.1)$$
$$u(0) = g(u).$$

where  $0 < \alpha < 1$ ,  ${}^C D_t^\alpha$  is the  $\alpha$ -order Caputo fractional derivative operator,  $f, g$  are functions to be specified later.

Let  $X$  be a separable Banach space endowed with norm  $\|\cdot\|$ ,  $A: D(A) \subset X \rightarrow X$  the infinitesimal generator of a strongly continuous semigroup of bounded linear operators  $\{T(t)\}_{t \geq 0}$ ,  $D(A)$  the domain of  $A$ .

In recent times, the theory of fractional differential equations has attracted many researchers with greater interest due to their many applications in the fields like physics, chemistry, biology, finance et al. Major references inherited from the books of Podlubny [17], Samko et al [18], Kilbas et al [9] and the papers of Nigmatullin [14], Meerschaert et al [13], Hahn et al [7], Li et al [10], Orisingher et al [16].

Byszewski [4] has initiated the study of the semilinear evolution nonlocal Cauchy problem. The nonlocal condition can be applied in physics with better effect in applications than the classical initial condition since nonlocal conditions

are usually more precise for physical measurements than the classical initial condition. Lin and Liu [11] studied semilinear integrodifferential equations with nonlocal Cauchy problems under Lipchitz-type conditions. Ntouyas and Tsamatos [15] studied the global existence of solutions semilinear evolution equations with nonlocal conditions through an application of fixed point analysis. Fu and Ezzinbi [6] studied the existence of mild and strong solutions of semilinear neutral functional differential evolution equations with nonlocal conditions by applying fractional power of operators and Sadovskii's fixed point theorem.

Xue [19] studied the existence of mild solutions for semilinear differential equations with nonlocal initial conditions in separable Banach spaces. Xue [20] discussed the semilinear nonlocal differential equations when the semigroup  $T(t)$  generated by the coefficient operator is compact and the nonlocal term  $g$  is not compact. Applying Sadovskii's fixed point theorem and Schauder's fixed point theorem, Fan and Li [5] studied the existence for impulsive semilinear differential equations with nonlocal conditions.

We shall study in this article, the existence of mild solutions of (1.1) by using the Hausdorff measure of compactness and fixed point theorems. We assume that the semigroup  $T(t)$  generated by the coefficient operator is equicontinuous. The compactness of  $T(t)$  of  $f$  and the Lipchitz condition of  $f$  are the special cases our conditions. Therefore, the results in this paper generalize and improve

some of previous ones in this field.

We organized the article in a manner such that Section 2 is containing some preliminaries about fractional calculus and the Hausdorff's measure of compactness and Section 3 is containing the existence result.

## 2. Preliminaries

Let  $(X, \|\cdot\|)$  be a separable Banach space and  $\mathbb{R}_+ = [0, \infty)$ . we denote by  $C([0, b]; X)$  the space of  $X$ -valued continuous functions on  $[0, b]$  with the norm

$$\|u\|_C := \sup_{t \in [0, b]} \|u(t)\|$$

and by  $L^1([0, b]; X)$ , we denote the space of  $X$ -valued Bochner integrable functions  $u: [0, b] \rightarrow X$  with the norm

$$\|u\|_{L^1([0, b]; X)} = \int_0^b \|u(t)\| dt.$$

**Definition 2.1.** The Riemann-Liouville fractional integral of  $u: [0, b] \rightarrow X$  of order  $\alpha \in (0, \infty)$  is defined by

$$J_t^\alpha u(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} u(s) ds.$$

The Riemann-Liouville fractional derivative of  $u: [0, b] \rightarrow X$  of order  $\alpha \in (0, 1)$  is defined by

$$D_t^\alpha u(t) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dt} \int_0^t (t-s)^{-\alpha} u(s) ds.$$

The Caputo fractional derivative of  $u: [0, b] \rightarrow X$  of order  $\alpha \in (0, 1)$  is defined by

$${}^C D_t^\alpha u(t) = D_t^\alpha (u(t) - u(0)).$$

We recall the Hausdorff measure of noncompactness  $\beta_Y(\cdot)$  defined on a bounded subset  $B$  of Banach space  $Y$  by  $\beta_Y(B) = \inf \{\varepsilon > 0; B \text{ has a finite } \varepsilon\text{-net in } Y\}$

Some basic properties of  $\beta_Y(\cdot)$  are presented in the following lemma.

**Lemma 2.2.** Let  $Y$  be real Banach space and  $B, C \subseteq Y$  be bounded, the following properties are satisfied:

- (1)  $B$  is precompact if and only if  $\beta_Y(B) = 0$ ;
- (2)  $\beta_Y(B) = \beta_Y(\bar{B}) = \beta_Y(\text{conv} B)$ , where  $\bar{B}$  and  $\text{conv} B$  mean the closure and convex hull of  $B$  respectively;
- (3)  $\beta_Y(B) \leq \beta_Y(C)$  and  $B \subseteq C$ ;
- (4)  $\beta_Y(B + C) \leq \beta_Y(B) + \beta_Y(C)$  where  $B + C = \{x + y; x \in B, y \in C\}$ ;
- (5)  $\beta_Y(B \cup C) \leq \max\{\beta_Y(B), \beta_Y(C)\}$ ;
- (6)  $\beta_Y(\lambda B) = |\lambda| \beta_Y(B)$  for any  $\lambda \in \mathbb{R}$ ;
- (7) If the mapping  $Q: D(Q) \subseteq Y \rightarrow Z$  is Lipschitz continuous with constant  $k$ , then  $\beta_Z(QB) \leq k \beta_Y(B)$  for any bounded subset  $B \subseteq D(Q)$ , where  $Z$  is a Banach space;
- (8) If  $\{W_n\}_{n=1}^\infty$  is a decreasing of bounded closed nonempty subsets of  $Y$  and  $\lim_{n \rightarrow \infty} \beta_Y(W_n) = 0$ , then  $\bigcap_{n=1}^\infty W_n$  is nonempty and compact in  $Y$ . The map  $Q: W \subseteq Y \rightarrow Y$  is said to be a  $\beta_Y$ -contraction if there exists a positive constant  $k < 1$  such that  $\beta_Z(Q(C)) \leq k \beta_Y(C)$

for any bounded closed subset  $C \subseteq W$  where  $Y$  is a Banach space.

**Lemma 2.3.** (Darbo-Sadovskii). If  $W \subseteq Y$  is bounded closed and convex, the continuous map  $Q: W \rightarrow W$  is a  $\beta_Y$ -contraction, then the map  $Q$  has at least one fixed point in  $W$ .

In this article, without loss of generality, we denote the Hausdorff measure of noncompactness of  $X$  and  $C([0, b]; X)$ .

**Lemma 2.4.** If  $W \subset C([0, b]; X)$  is bounded and equicontinuous, then the set  $\beta(W(t))$  is continuous on  $[0, b]$  and

$$\beta(W) = \sup_{t \in [0, b]} \beta(W(t)).$$

**Lemma 2.5.** If  $\{u_n\}_{n=1}^\infty \subset L^1([0, b]; X)$  satisfies  $|u_n(t)| \leq \varphi(t)$  a.e. on  $[0, b]$  for all  $n \geq 1$  with some  $\varphi \in L^1([0, b]; \mathbb{R}_+)$ , then  $\beta\left(\left\{\bigcup_{n=1}^\infty \int_0^t u_n(s) ds\right\}\right) \leq \int_0^t \beta(\{u_n(s)\}) ds$ .

**Lemma 2.6.** A  $C_0$  semigroup  $T(t)$  is said to be equicontinuous, if the mapping  $t \rightarrow \{T(t)x; x \in B\}$  is equicontinuous at  $t > 0$  for all bounded set  $B$  in Banach space  $X$ .

**Lemma 2.7.** The Mainardi's function is defined by

$$M_\alpha(z) = \sum_{n=0}^\infty \frac{(-z)^n}{n! \Gamma(-\alpha n + 1 - \alpha)}, 0 < \alpha < 1. \quad (2.1)$$

where  $\Gamma$  is a Gamma function.

It is known that  $M_\alpha(z)$  satisfies the following equality [12]

$$\int_0^\infty r^\delta M_\alpha(r) dr = \frac{\Gamma(\delta+1)}{\Gamma(\alpha\delta+1)}, \delta > -1, \quad (2.2)$$

## 3. Main Results

In this section, an attempt is made to prove the existence of a mild solution of (1.1) by using the Hausdorff measure of noncompactness. The function  $g$  is assumed to be compact. A function  $u \in C([0, b]; X)$  is called a mild solution of the equation (1.1) if

$$u(t) = T_\alpha(t)g(u)$$

$$+ \int_0^t (t-s)^{\alpha-1} S_\alpha(t-s) \int_0^s f(s, \tau, u(\tau)) d\tau ds, \quad (3.1)$$

$$\text{where } T_\alpha(t) = \int_0^\infty M_\alpha(r) T(t^\alpha r) dr, t \geq 0, \quad (3.2)$$

$$S_\alpha(t) = \int_0^\infty \alpha r M_\alpha(r) T(t^\alpha r) dr, t \geq 0, \quad (3.3)$$

where  $M_\alpha(r)$  is the Mainardi's function.

**Remark 3.1.** If  $T(t)$  is equicontinuous, by (2.2), it is easy to show that  $T_\alpha(t)$ ,  $S_\alpha(t)$  are equicontinuous.

**Lemma 3.2.** Let  $0 < \alpha < 1$ . Let the semigroup  $T(t)$  be equicontinuous and also let  $\varphi \in L^1([0, b]; \mathbb{R}_+)$ . Then the set

$$\left\{ \int_0^t (t-s)^{\alpha-1} S_\alpha(t-s) u(s) ds, \|u(s)\| \leq \varphi(s) \text{ a.e.} \right.$$

$\left. s \in [0, b] \right\}$  is equicontinuous for  $t \in [0, b]$ .

*Proof.* For  $0 \leq t_1 \leq t_2 \leq b$ , we have

$$\begin{aligned}
& \left\| \int_0^{t_2} (t_2 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds - \int_0^{t_1} (t_1 - s)^{\alpha-1} S_\alpha(t_1 - s) u(s) ds \right\| \\
&= \left\| \int_0^{t_1} (t_2 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds - \int_0^{t_1} (t_1 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds \right. \\
&+ \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds + \int_0^{t_1} (t_1 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds \\
&\left. - \int_0^{t_1} (t_1 - s)^{\alpha-1} S_\alpha(t_1 - s) u(s) ds \right\| \\
&\leq \left\| \int_0^{t_1} ((t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}) S_\alpha(t_2 - s) u(s) ds \right\| \\
&+ \left\| \int_0^{t_1} (t_1 - s)^{\alpha-1} (S_\alpha(t_1 - s) - S_\alpha(t_2 - s)) u(s) ds \right\| \\
&+ \left\| \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds \right\| \\
&\leq \int_0^{t_1} \|((t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}) S_\alpha(t_2 - s) u(s)\| ds \\
&+ \left\| \int_0^{t_1} (t_1 - s)^{\alpha-1} \|S_\alpha(t_2 - s) - S_\alpha(t_1 - s)\| \|u(s)\| ds \right\| \\
&+ \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} \|S_\alpha(t_2 - s) u(s)\| ds.
\end{aligned}$$

From this inequality it follows that

$$\left\| \int_0^{t_2} (t_2 - s)^{\alpha-1} S_\alpha(t_2 - s) u(s) ds - \int_0^{t_1} (t_1 - s)^{\alpha-1} S_\alpha(t_1 - s) u(s) ds \right\| \rightarrow 0$$

as  $t_1 \rightarrow t_2$ . The proof is complete.

**Lemma 3.3.** Suppose  $b \geq 0, \sigma > 0$  and  $a(t)$  is a nonnegative function locally integrable on  $0 \leq t < T$  (some  $T \leq +\infty$ ), and suppose  $c(t)$  is nonnegative and locally integrable on  $0 \leq t < T$  with

$$c(t) \leq a(t) + b \int_0^t (t - s)^{\sigma-1} c(s) ds$$

on this interval. Then

$$c(t) \leq a(t) + \mu \int_0^t E'_\sigma(\mu(t - s)) a(s) ds, 0 \leq t < T,$$

where  $\mu = (b\Gamma(\sigma))^{1/\sigma}$ ,

$$E_\sigma(z) = \sum_{n=0}^{\infty} z^{n\sigma} / \Gamma(n\sigma + 1),$$

$$E'_\sigma(z) = \frac{d}{dz} E_\sigma(z).$$

If  $a(t) \equiv a$ , constant, then  $c(t) \leq aE_\sigma(\mu t)$ .

To prove the main results, we use the following assumptions:

(A1) The  $C_0$  semigroup  $T(t)$  is equicontinuous, and there exists a constant  $M \geq 1$  such that

$$\sup_{t \geq 0} \|T(t)\| \leq M.$$

(A2)  $g: C([0, b]; X) \rightarrow X$  is continuous and compact, and there exists a constant  $N > 0$  such that  $\|g(u)\| \leq N$ ,  $u \in C([0, b]; X)$ .

(A3)  $f: [0, b] \times [0, b] \times X \rightarrow X$  satisfied the Caratheodory condition; i.e.  $f(\cdot, \cdot, x)$  is measurable for all  $x \in X$ , and  $f(t, s, \cdot)$  is continuous for a.e.  $t \in [0, b]$ .

(A4) There exists a function  $h: [0, b] \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$  such that  $h(\cdot, s) \in L^1([0, b]; \mathbb{R}_+)$  for all  $s \geq 0$ ,  $h(t, \cdot)$  is continuous and increasing for a.e.  $t \in [0, b]$ , and  $\|f(t, s, x)\| \leq h(t, \|x\|)$  for a.e.  $t \in [0, b]$  and all  $x \in X$ . moreover, there exists at least one solution to the following scalar equation:

$$q(t) = MN$$

$$+ \frac{\alpha M}{\Gamma(\alpha+1)} \int_0^t (t - s)^{\alpha-1} \int_0^s h(s, q(\tau)) d\tau ds, t \in [0, b]. \quad (3.4)$$

(A5) There exists a constant  $\gamma > 0$  such that

$$\beta(f(t, s, B(t))) \leq \gamma \beta(B(t)) \quad (3.5)$$

for a.e.  $t, s \in [0, b]$  and every bounded  $B \subset C([0, b]; X)$ .

**Lemma 3.4.** Assume that conditions (A1) to (A5) are satisfied. Then the nonlocal problem (1.1) has at least one mild solution on  $[0, b]$ .

*Proof.* Define the mapping

$$F: C([0, b]; X) \rightarrow C([0, b]; X) \text{ by}$$

$$(Fu)(t) = T_\alpha(t)g(u) + \int_0^t (t - s)^{\alpha-1}$$

$$\cdot S_\alpha(t - s) \int_0^s f(s, \tau, u(\tau)) d\tau ds, t \in [0, b]. \quad (3.6)$$

It is obvious that the fixed point of  $F$  is the mild solution of (1.1) and it is easy to show that  $F$  is continuous on  $C([0, b]; X)$ . From (3.2), (2.2) and (A1), it follows that

$$\|T_\alpha(t)\| \leq M, t \geq 0. \quad (3.7)$$

From (3.3) and (2.2), it follows that

$$\|S_\alpha(t)\| \leq \alpha M \int_0^\infty r M_\alpha(r) dr \leq \frac{\alpha M}{\Gamma(\alpha+1)}, t \geq 0. \quad (3.8)$$

Set  $Q_0 = \{u \in C([0, b]; X), \|u(t)\| \leq q(t), t \in [0, b]\}$ . Then  $Q_0 \subset C([0, b]; X)$  is bounded and convex. Define  $Q_1 = \overline{\text{conv}} F(Q_0)$ , where  $\overline{\text{conv}}$  means the closure of the convex hull in  $C([0, b]; X)$ . From Remark 3.1, Lemma 3.2, (A4), the equicontinuity of  $T(t)$ , compactness of  $g$  and  $Q_0 \subset C([0, b]; X)$ , it follows that  $Q_1 \subset C([0, b]; X)$  is bounded closed convex and equicontinuous on  $[0, b]$ . For every  $u \in F(Q_0)$ ,

$$\|u(t)\| \leq MN$$

$$+ \frac{\alpha M}{\Gamma(\alpha+1)} \int_0^t (t - s)^{\alpha-1} \int_0^s h(s, q(\tau)) d\tau ds = q(t).$$

This implies  $Q_1 \subset Q_0$ . We denote the following equality  $Q_{n+1} = \overline{\text{conv}} F(Q_{n+1})$ ,  $n = 1, 2, \dots$ . It is easy to show that  $\{Q_{n+1}\}_{n=1}^\infty$  is a decreasing sequence of equicontinuous on  $[0, b]$ , and is bounded closed convex subsets of  $C([0, b]; X)$ .

Since  $X$  is separable, then  $C([0, b]; X)$  is separable, hence there exists a dense subset  $\{u_k\}_{k=1}^\infty$  of  $Q_n$ . From Lemma 2.2, it follows that

$$\begin{aligned}\beta(Q_{n+1}(t)) &= \beta(\cup_{k=1}^\infty (Fu_k)(t)) \\ &\leq \beta(\{T_\alpha(t)g(\cup_{k=1}^\infty u_k) \\ &+ \cup_{k=1}^\infty \int_0^t (t-s)^{\alpha-1} S_\alpha(t-s) \int_0^s f(s, \tau, u_k(\tau)) d\tau ds\})\end{aligned}$$

Since  $g$  is compact, by Lemma 2.5, we have

$$\begin{aligned}\beta(Q_{n+1}(t)) &\leq \\ \beta(\cup_{k=1}^\infty \int_0^t (t-s)^{\alpha-1} S_\alpha(t-s) \int_0^s f(s, \tau, u_k(\tau)) d\tau ds) \\ &\leq \int_0^t (t-s)^{\alpha-1} \beta(\{S_\alpha(t-s) \int_0^s f(s, \tau, \cup_{k=1}^\infty u_k(\tau)) d\tau ds\}) \\ &\leq \int_0^t (t-s)^{\alpha-1} \beta(S_\alpha(t-s) \int_0^s f(s, \tau, Q_n(\tau)) d\tau) ds \\ &\leq \frac{\alpha M}{\Gamma(\alpha+1)} \int_0^t (t-s)^{\alpha-1} \beta(\int_0^s f(s, \tau, Q_n(\tau)) d\tau) ds. \quad (3.9)\end{aligned}$$

By (3.5) and (3.9), we have

$$\beta(Q_{n+1}(t)) \leq \frac{\alpha \gamma M}{\Gamma(\alpha+1)} \int_0^t (t-s)^{\alpha-1} \beta(Q_n(\tau)) d\tau ds. \quad (3.10)$$

Since  $Q_n$  is decreasing with respect to  $n$ , we define

$$\theta(t) = \lim_{n \rightarrow \infty} \int_0^t \beta(Q_n(\tau)) d\tau, \quad t \in [0, b]. \quad (3.11)$$

Taking  $n \rightarrow \infty$  to both sides of (3.10), we have

$$\theta(t) \leq \frac{\alpha \gamma M}{\Gamma(\alpha+1)} \int_0^t (t-s)^{\alpha-1} \theta(s) ds. \quad (3.12)$$

By Lemma 3.3, we obtain the result  $\theta(t) = 0, t \in [0, b]$ . By Lemma 2.3,

$$\lim_{n \rightarrow \infty} \beta(Q_n) = 0.$$

By Lemma 2.2, it follows that  $Q = \cap_{n=1}^\infty Q_n$  is convex compact in  $C([0, b]; X)$  and  $F(Q) \subset Q$ . From the Schauder fixed point theorem, there exists at least one fixed point  $u \in Q$ , which is mild solution of (1.1).

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